

Учимся готовить C++ корутины
на практике

Understanding C++ coroutines by example

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 @cpp_ape

R&D Align Technology

align

No decent user facing support in C++20

Use cppcoro by Lewis Baker

<https://github.com/lewissbaker/cppcoro>

Thanks for coming!

Gameplan

- Iteration 0: my first coroutine
 - What is a C++ coroutine?
 - Demystifying compiler magic
- Iteration 1: awaiting tasks
 - Making tasks awaitable
 - Writing awaitable types
- Iteration 2:
 - Getting tasks result
 - Thread safety
- Analysis of the approach

Iteration 0: my first coroutine

```
Task<int> foo() {  
    co_return 42;  
}
```

A function is a coroutine if it contains one of these:

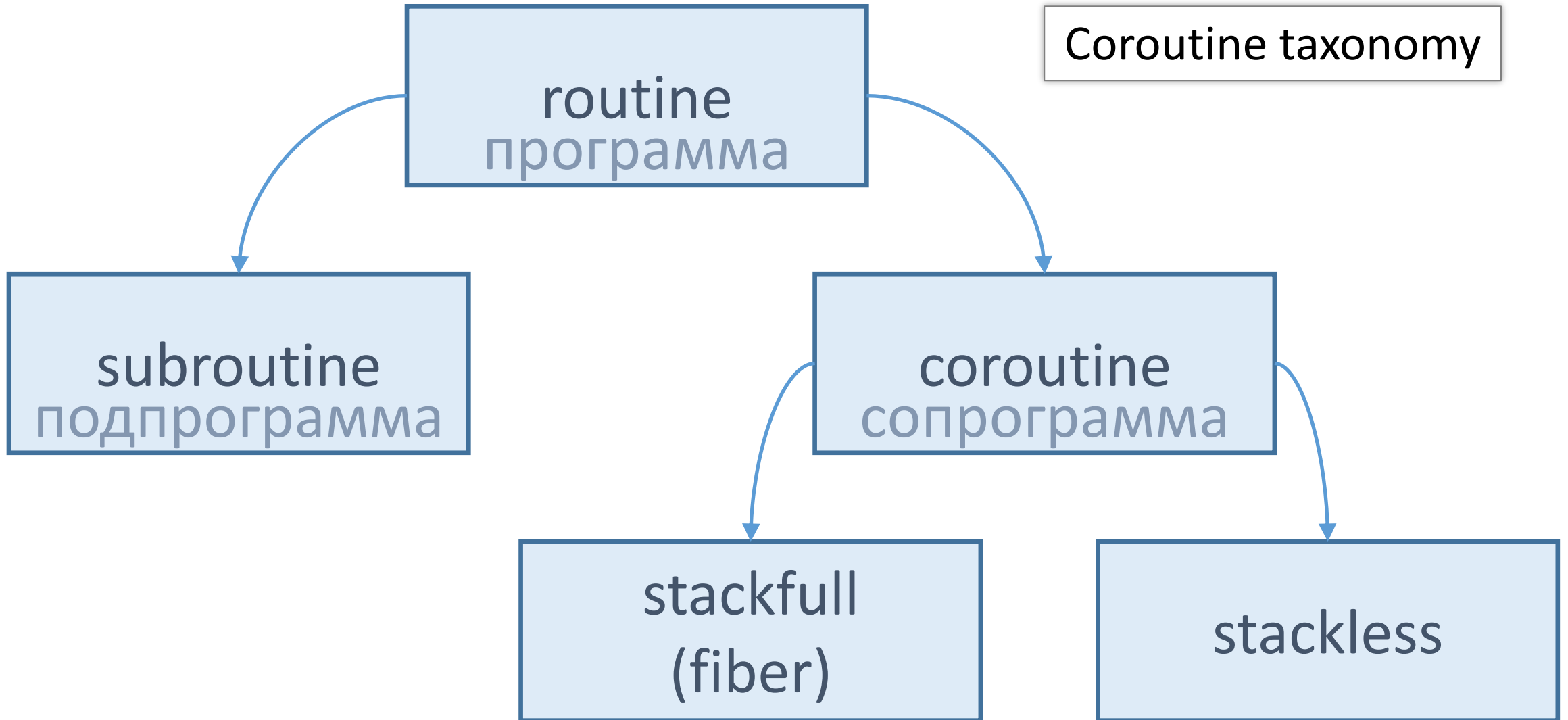
`co_return` (coroutine return statement)

`co_await` (await expression)

`co_yield` (yield expression)

What is a C++ coroutine?

Coroutine taxonomy



What is a C++ coroutine?

Simula

From Wikipedia, the free encyclopedia

*This article is about the programming language. For the village in Estonia, see [Simula, Estonia](#).
Not to be confused with [Simulia](#).*

Simula is the name of two [simulation programming languages](#), Simula I and Simula 67, developed in the 1960s at the Norwegian Computing Center in Oslo, by Ole Johan Dahl and Kristen Nygaard. Syntactically, it is a fairly

Simula

Simula 67 introduced [objects](#),^{[1]:2, 5.3} [classes](#),^{[1]:1.3.3, 2} [inheritance](#) and [subclasses](#),^{[1]:2.2.1} [virtual procedures](#),^{[1]:2.2.3} [coroutines](#),^{[1]:9.2} and [discrete event simulation](#),^{[1]:14.2} and features [garbage collection](#).^{[1]:9.1} Also other forms of [subtyping](#) (besides inheriting subclasses) were introduced in Simula derivatives.^[*citation needed*]

oriented languages today.

Simula has been used in a wide range of applications such as simulating VLSI designs, [process modeling](#), [protocols](#), [algorithms](#), and other applications such as [typesetting](#), [computer graphics](#), and [education](#). The

discipline

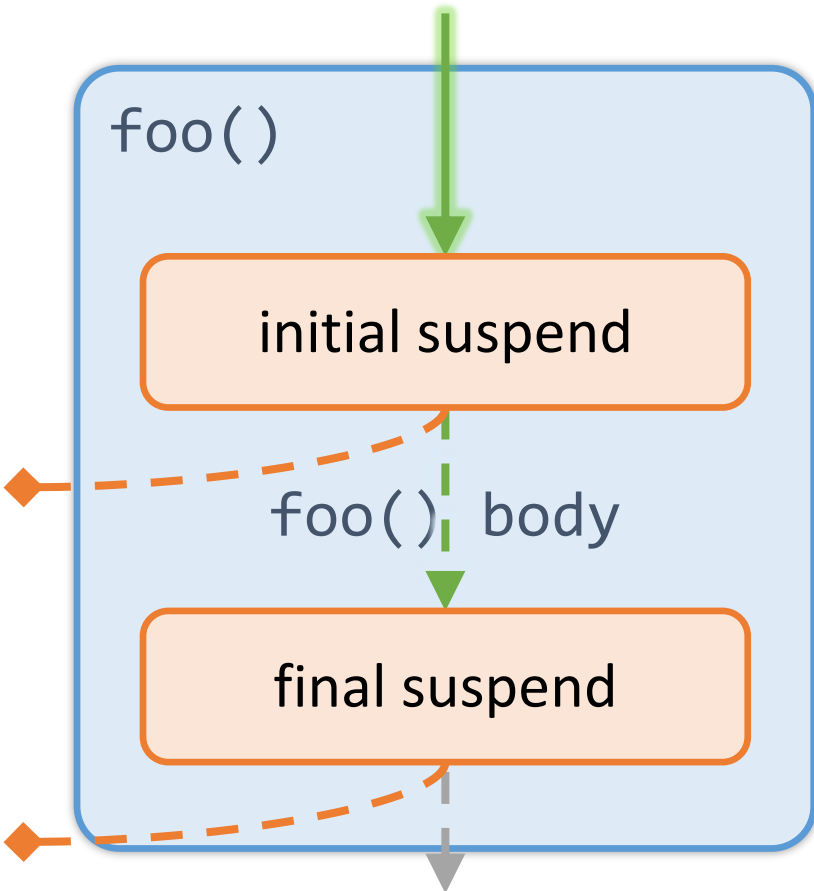
Implementation language [ALGOL 60](#) (primarily; some components [Simscrip](#))

OS [Unix-like](#), [Windows](#)

Website <http://www.simula67.info/>

What is a C++ coroutine?

```
Task<int> foo() {  
    co_return 42;  
}
```



A coroutine behaves as if its *function-body* were replaced by:

```
{  
    promise-type promise promise-constructor-arguments ;  
    try {  
        co_await promise.initial_suspend() ;  
        function-body  
    } catch ( ... ) {  
        if (!initial-await-resume-called)  
            throw ;  
        promise.unhandled_exception() ;  
    }  
    final-suspend :  
        co_await promise.final_suspend() ;  
}
```

What is a C++ coroutine?

```
Task<int> foo() {  
    co_return 42;  
}
```



A coroutine behaves as if its *function-body* were replaced by:

```
{  
    promise-type promise promise-constructor-arguments ;  
    try {  
        co_await promise.initial_suspend() ;  
        function-body  
    } catch ( ... ) {  
        if (!initial-await-resume-called)  
            throw ;  
        promise.unhandled_exception() ;  
    }  
    final-suspend :  
    co_await promise.final_suspend() ;  
}
```

Transformation by the compiler

```
Task<int> foo() {  
    co_return 42;  
}
```

original code



transformed code



```
Task<int> foo() {  
    struct CoroFrame {  
        Task<int>::promise_type promise;  
        bool initial_await_resume_called = false;  
        int state = 0;  
        void operator()() {  
  
            co_return 42;  
  
        }  
    };  
    auto coroFrame = new CoroFrame;  
    auto returnObject{ coroFrame->promise.get_return_object() };  
    (*coroFrame)();  
    return returnObject;  
}
```

Transformation by the compiler

```
Task<int> foo() {  
    co_return 42;  
}
```

```
Task<int> foo() {  
    struct CoroFrame {  
        Task<int>::promise_type promise;  
        bool initial_await_resume_called = false;  
        int state = 0;  
        void operator>() {  
            try {
```

```
Task<int> foo() {  
    struct CoroFrame {  
        Task<int>::promise_type promise;  
        bool initial_await_resume_called = false;  
        int state = 0;  
        void operator>() { /*...*/ }  
    };  
    auto coroFrame = new CoroFrame;  
    auto returnObject{ coroFrame->promise.get_return_object() };  
    (*coroFrame)();  
    return returnObject;  
}  
    return returnObject;  
}
```

coroutine
frame

ct() };

Transformation by the compiler

```
Task<int> foo() {  
    co_return 42;  
}
```

```
Task<int> foo() {  
    struct CoroFrame {  
        Task<int>::promise_type promise;  
        bool initial_await_resume_called = false;  
        int state = 0;  
    };  
    auto operator()() {
```

```
        void operator()  
        try {  
            co_await promise.initial_suspend();  
            co_return 42;  
        }  
        catch (...) {  
            if (!initial_await_resume_called)  
                throw;  
            promise.unhandled_exception();  
        }  
        final_suspend() {  
            co_await promise.initial_suspend();  
        }  
    }  
}
```

```
    object() };
```

Transformation by the compiler

```
Task<int> foo() {  
    co_return 42;  
}
```

```
Task<int> foo() {  
    struct CoroFrame {  
        Task<int>::promise_type promise;  
        bool initial_await_resume_called = false;  
        int state = 0;  
        void operator()() {
```

```
void operator()() {  
    try {  
        co_await promise.initial_suspend();  
        promise.return_value(42); goto final_suspend;  
    }  
    catch (...) {  
        if (!initial_await_resume_called)  
            throw;  
        promise.unhandled_exception();  
    }  
    final_suspend:  
    co_await promise.final_suspend();  
}
```

```
object() };
```

```
}
```

Transformation by the compiler

```
Task<int> foo() {  
    co_return 42;  
}
```

Sequence of operations:

```
Task<int>::promise_type promise;  
promise.get_return_object();  
promise.initial_suspend();  
promise.return_value(42);  
promise.unhandled_exception();  
promise.final_suspend();
```

```
Task<int> foo() {  
    struct CoroFrame {  
        Task<int>::promise_type promise;  
        bool initial_await_resume_called = false;  
        int state = 0;  
        void operator()() {  
            try {  
                co_await promise.initial_suspend();  
                promise.return_value(42); goto final_suspend;  
            }  
            catch (...) {  
                if (!initial_await_resume_called)  
                    throw;  
                promise.unhandled_exception();  
            }  
            final_suspend:  
                co_await promise.final_suspend();  
        }  
    };  
    auto coroFrame = new CoroFrame;  
    auto returnObject{ coroFrame->promise.get_return_object() };  
    (*coroFrame)();  
    return returnObject;  
}
```

Task type

```
template<typename T> struct Promise;
```

```
struct CoroDeleter {  
    template<typename Promise>  
    void operator()(Promise *promise) const noexcept {  
        using CoroHandle = std::coroutine_handle<Promise>;  
        CoroHandle::from_promise(*promise).destroy();  
    }  
};  
template<typename T>  
using PromisePtr = std::unique_ptr<Promise<T>, CoroDeleter>;
```

```
    PromisePtr<T> promise = nullptr;
```

```
    template<typename> friend struct Promise;  
};
```

Task type

```
template<typename T> struct Promise;
```

```
template<typename T>  
struct [[nodiscard]] Task {  
    using promise_type = Promise<T>;  
    Task() = default;
```

```
private:
```

```
    Task(Promise<T> *promise) : promise{ promise } {}
```

```
    PromisePtr<T> promise = nullptr;
```

```
    template<typename> friend struct Promise;
```

```
};
```

Promise type

```
void return_value(U &&value)
    noexcept(std::is_nothrow_assignable_v<decltype(result), decltype(std::forward<U>(value))>)
{
    Task<int> foo() {
        struct CoroFrame {
            void operator>() {
                T &&getResult() {
                    if (result.index() == 2)
                        std::rethrow_exception(std::get<2>(result));
                    return std::move(std::get<1>(result));
                }
                (*coroFrame)();
                return returnObj;
            }
            catch {
                final_suspend:
                co_await promise.final_suspend();
            }
            promise.unhandled_exception();
        }
    }
};
```

Iteration 0: my first coroutine

```
Task<int> foo() {  
    std::cout << "foo(): about to return\n";  
    co_return 42;  
}
```

```
auto task = foo();
```

output:

```
foo(): about to return
```

Iteration 0: my first coroutine

```
Task<void> foo
    co_return;
}
```

```
template<typename T>
struct Promise
    //...
    void return_
    //...
};
```



```
    final_suspend();
    ; goto final_suspend;
```

```
    suspend();
```


Iteration 1: awaiting tasks

```
Task<int> bar() {  
    const auto result = foo();  
    const int i = co_await result;  
    co_return i + 23;  
}
```

Awaiting: rough idea

```
co_await result;
```



```
auto awaitable{ getAwaitable(result) };  
if (!awaitable.await_ready()) {  
    awaitable.await_suspend(thisCoroHandle);  
    // suspend coroutine  
}
```

```
resume:
```

```
awaitable.await_resume();
```

Transformation by the compiler

```
Task<int> bar() {  
    const auto result = foo();  
    const int i = co_await result;  
    co_return i + 23;  
}
```

original code

transformed code

```
Task<int> bar() {  
    struct CoroFrame {  
        Task<int>::promise_type promise;  
        bool initial_await_resume_called = false;  
        int state = 0;  
        //...  
        void operator()();  
    };  
    auto coroFrame = new CoroFrame;  
    auto returnObject{  
        coroFrame->promise.get_return_object()  
    };  
    (*coroFrame)();  
    return returnObject;  
}
```

Transformation by the compiler

```
void operator()() {  
    try {  
        switch (state)  
        {  
            case 0:  
                break;  
            case 1:  
                goto initialResume;  
            case 2:  
                goto resume2;  
            default:  
                break; //bad 😞  
        }  
        //...  
    }  
}
```

```
struct CoroFrame {  
    Task<int>::promise_type promise;  
    bool initial_await_resume_called = false;  
    int state = 0;  
    //...  
    void operator()();  
};
```

Transformation by the compiler

```
void operator>() {  
    //...  
    state = 1;  
    awaitable0 ← ??? ---  
    if (!awaitable0->aw  
        awaitable0->await  
        // suspend  
        return;  
}  
initialResume:  
    initial_await_resume_called = true;  
    awaitable0->await_resume();  
    //...
```

```
struct CoroFrame {  
    Task<int>::promise_type promise;  
    bool initial_await_resume_called = false;  
    int state = 0;  
    std::optional<Awaitable0> awaitable0;  
    //...  
    void operator>()();  
};
```

Transformation by the compiler

```
void operator()() { co_await promise.initial_suspend();
  //...
  state = 1;
  awaitable0.emplace(getAwaitable(promise.initial_suspend()));
  if (!awaitable0->await_ready()) {
    awaitable0->await_suspend(thisCoroHandle);

    struct suspend_never {
      bool await_ready() noexcept {
        return true;
      }
      void await_suspend(coroutine_handle<>) noexcept {}
      void await_resume() noexcept {}
    };
  
  //};
```

Transformation by the compiler

```
void operator>() {  
    //...
```

```
const auto result = foo();  
const int i = co_await result;
```

```
    const auto result = foo();
```

```
    state = 2;
```

```
    awaitable1.emplace(getAwaitable(result));
```

```
    if (!awaitable1->await_ready() {
```

```
        auto coro = awaitable1->await_suspend(thisCoroHandle);
```

current coroutine to **suspend**

```
struct Awaitable {  
    bool await_ready() const noexcept;  
    using CoroHandle = std::coroutine_handle<>;  
    CoroHandle await_suspend(CoroHandle) const noexcept;  
    T &&await_resume() const;  
};
```

```
    //...
```

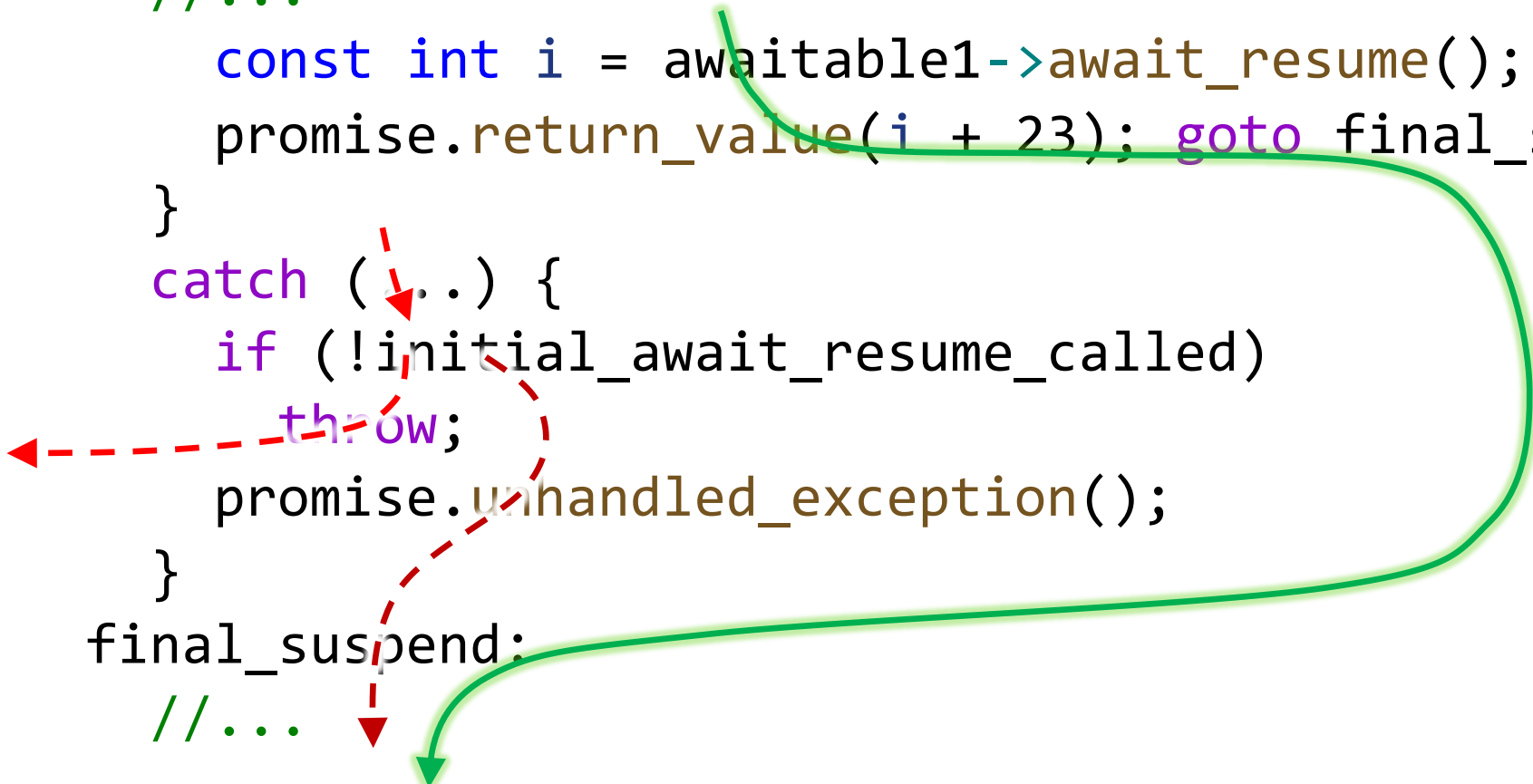
Transformation by the compiler

```
void operator()() {  
    //...  
    const auto result =  
    state = 2;  
    awaitable1.emplace(  
    if (!awaitable1->aw  
        auto coro = await  
        // suspend  
        coro();  
        return;  
    }  
resume2:  
    const int i = awaitable1->await_resume();  
    //...  
}
```

```
struct CoroFrame {  
    Task<int>::promise_type promise;  
    bool initial_await_resume_called = false;  
    int state = 0;  
    std::optional<Awaitable0> awaitable0;  
    std::optional<Awaitable1> awaitable1;  
    void operator()();  
};
```


Transformation by the compiler

```
void operator()() { co_return i + 23;  
  //...  
  const int i = awaitable1->await_resume();  
  promise.return_value(i + 23); goto final_suspend;  
}  
catch (...) {  
  if (!initial_await_resume_called)  
    throw;  
  promise.unhandled_exception();  
}  
final_suspend:  
  //...
```



Transformation by the compiler

```
void operator()() { co_await promise.final_suspend();
    //...
    final_suspend:
        auto finalAwaitable{ getAwaitable(promise.final_suspend()) };
        if (!finalAwaitable.await_ready()) {
            finalAwaitable.await_suspend(thisCoroHandle);

            struct suspend_always {
            }
            bool await_ready() noexcept {
            de    return false;
            }
            }
            void await_suspend(coroutine_handle<>) noexcept {}
            void await_resume() noexcept {}
            };

```

Awaiting: Task

```
template<typename T>
struct [[nodiscard]] Task {
    using promise_type = Promise<T>;
    Task() = default;
    auto operator co_await() const noexcept;

private:
    Task(Promise<T> *promise) : promise{ promise } {}

    PromisePtr<T> *promise = nullptr;

    template<typename> friend struct Promise;
};
```

Task::operator co_await

```
auto operator co_await() const noexcept {  
    struct Awaitable {  
        //...  
        Promise<T> &promise;  
    };  
    return Awaitable{ *promise };  
}
```

Task::operator co_await

```
struct Awaitable {  
    bool await_ready() const noexcept {  
        return promise.isReady();  
    }  
    using CoroHandle = std::coroutine_handle<>;  
    CoroHandle await_suspend(CoroHandle continuation) const noexcept {  
        promise.continuation = continuation;  
        return std::coroutine_handle<Promise<T>>::from_promise(promise);  
    }  
    T &&await_resume() const {  
        return promise.getResult();  
    }  
  
    Promise<T> &promise;  
};
```

symmetric control transfer

current coroutine is suspended and suspended coroutine is returned and resumed

Awaiting: Promise

```
template<typename T>
struct Promise {
    //...
    // std::suspend_always final_suspend() noexcept { return {}; }
    auto final_suspend() noexcept {
        struct FinalAwaitable { /*...*/ };
        return FinalAwaitable{};
    }
    //...
    std::variant<std::monostate, T, std::exception_ptr> result;
    std::coroutine_handle<> continuation;
};
```

Awaiting: Promise

```
template<typename T>  
struct Promise {
```

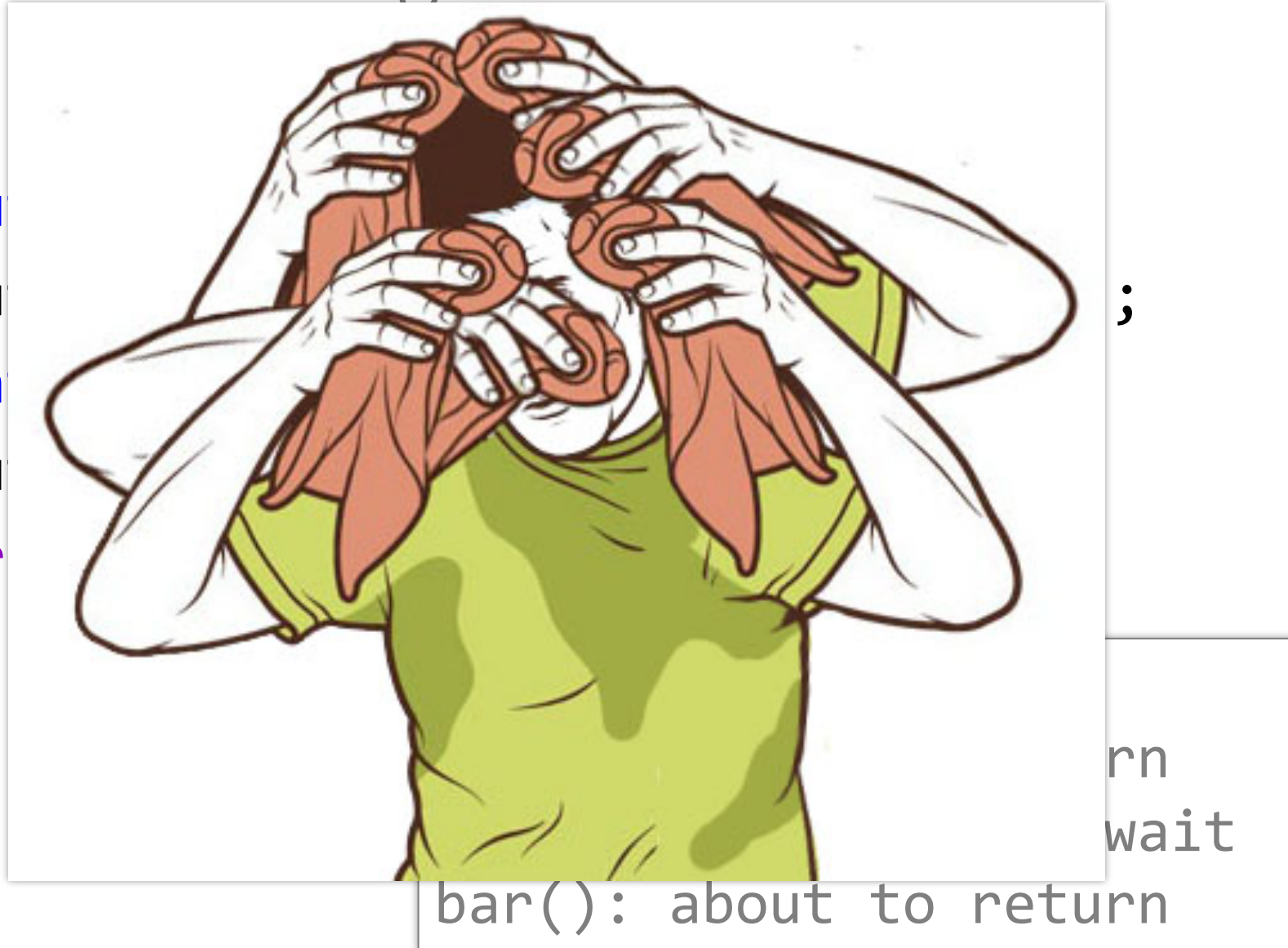
```
    struct FinalAwaitable {  
        bool await_ready() const noexcept { return false; }  
        void await_suspend(std::coroutine_handle<Promise<T>> thisCoro) {  
            auto &promise = thisCoro.promise();  
            if (promise.continuation)  
                promise.continuation();  
        }  
        void await_resume() const noexcept {}  
    };
```

```
        std::coroutine_handle<> continuation;
```

```
};
```

Iteration 1: awaiting tasks

```
Task<int>  
  const auto  
  std::cout  
  const in  
  std::cout  
  co_return  
}  
  
auto task
```





Helpful tip

Write constructor and destructor for promise types.

```
template<typename T>
struct Promise {
    Promise() {
        std::cout << "Promise: ctor\n";
    }
    ~Promise() {
        std::cout << "Promise: dtor\n";
    }
    //...
};
```

Writing an awaitable

```
struct Sleep {  
    bool await_ready() const noexcept {  
        return duration == duration.zero();  
    }  
    void await_suspend(std::coroutine_handle<> coro) const {  
        std::this_thread::sleep_for(duration);  
        coro();  
    }  
    void await_resume() const noexcept {}  
  
    std::chrono::milliseconds duration;  
};
```

suspended coroutine

resumes the suspended coroutine

lead to sleep

Writing an awaitable

```
Task<void> sleepy() {  
    std::this_thread::sleep_for(1s);  
    co_await some_async_operation();  
    std::this_thread::sleep_for(1s);  
}  
auto ta
```



Well that just sounds like `std::this_thread::sleep_for()` with extra steps

leep
turn

Asynchronously reading a file

```
struct AsyncReadFile {
    AsyncReadFile(std::filesystem::path path) :
        path{ std::move(path) } {}
    bool await_ready() const noexcept { return false; }
    void await_suspend(std::coroutine_handle<> coro);
    std::string await_resume() noexcept {
        return std::move(result);
    }
}

private:
    std::filesystem::path path;
    std::string result;
};
```

Asynchronously reading a file

```
void await_suspend(std::coroutine_handle<> coro) {  
    auto work = [this, coro]() mutable {  
        std::cout << tid << " worker thread: opening file\n";
```

Clang:
no matching function for call to object of type 'const std::coroutine_handle<>'
include/c++/v1/experimental/coroutine:113:10: note: candidate function not viable:
'this' argument has type 'const std::coroutine_handle<>', but method is not marked const

```
        std::cout << tid << " worker thread: resuming coro\n";  
        coro();  
        std::cout << tid << " worker thread: exiting\n";  
    };  
    std::thread{ work }.detach();  
}
```

Asynchronously reading a file

```
void await_suspend(std::coroutine_handle<> coro) {  
    auto work = [this, coro]() mutable {  
        std::cout << tid << " worker thread: opening file\n";  
        path };  
        thread: reading file\n";  
        f_iterator<char>{stream},  
        f_iterator<char>{ });  
        thread: resuming coro\n";  
        thread: exiting\n";  
    std::thread{ work }.detach();  
}
```



Asynchronously reading a file

```
Task<size_t> readFile() {  
    std::cout << tid << " readFile(): about to read file async\n";  
    const auto result = co_await AsyncReadFile{ "main.cpp" };  
    std::cout << tid << " readFile(): about to return (size "  
        << result.size() << ")\n";  
    co_return result.size();  
}  
  
int main() {  
    auto task = readFile();  
}
```

```
output:  
Promise: ctor  
(tid=38216) readFile(): about to read file async  
Promise: dtor
```

Asynchronously reading a file

Thread A

```
Task<size_t> readFile() {  
    const auto result =  
        co_await AsyncReadFile{ "main.cpp" };  
    co_return contents.size();  
}  
  
exit(0);
```

coroutine is suspended

Thread B

```
auto work = [this, coro]() {  
    //...  
    coro();  
    //...  
};
```


Iteration 2

In which we learn how to get result out of a task and make awaiting thread-safeish

Getting result from task

Where is the result?

```
auto task = bar();
```

```
template<typename T>
struct [[nodiscard]] Task {
    //...
private:
    //
    PromisePtr<T> promise;
};
```

```
template<typename T>
struct Promise {
    //...
    std::variant<std::monostate, T, std::exception_ptr> result;
    std::coroutine_handle<> continuation;
};
```

Getting result from task

Thread A

```
auto task = baz();  
//...  
// are we there yet?  
auto result =  
    getResult(task);
```

Thread B

continues to execute on thread B

```
Task<void> baz() {  
    ↪ //...  
    co_return;  
}
```

Getting result from task

Thread A

```
auto task = baz();
```

```
std::future<void> result;  
result.get();
```

Thread B

continues to execute on thread B

```
Task<void> baz() {
```

```
    //...
```

```
    co_return;
```

```
    std::promise<void> promise;  
    promise.set_value();  
}
```

continuation

Getting result from task

```
template<typename T>
SyncWaitImpl<ResultOfAwait<T&&>> syncWaitImpl(T &&task) {
    co_return co_await std::forward<T>(task);
}
```

```
template<typename T>
auto syncWait(T &&task) {
    return syncWaitImpl(std::forward<T>(task))
        .result.get();
}
```

Getting result from task

```
template<typename T>
struct SyncWaitImpl {
    struct promise_type {
        template<typename T>
        //...
        auto syncWait(T &&task) {
            return syncWaitImpl(std::forward<T>(task))
                .result.get();
        }
    };
    std::future<T> result;
};
```

Getting result from task

```
struct promise_type {
    SyncWaitImpl get_return_object() {
        return { promise.get_future() };
    }
    std::suspend_never initial_suspend() noexcept { return {}; }
    std::suspend_never final_suspend() noexcept { return {}; }
    void return_value(T &&value) {
        promise.set_value(std::move(value));
    }
    void unhandled_exception() {
        promise.set_exception(std::current_exception());
    }

    std::promise<T> promise;
};
```

Getting result from task

```
auto task = bar();  
auto result = syncWait(task);
```


Getting result from task

```
Task<int> foo() {
    std::cout << "foo(): about to return\n";
    co_return 42;
}
Task<int> bar() {
    const auto result = foo();
    std::cout << "bar(): about to co_await\n";
    const int i = co_await result;
    std::cout << "bar(): about to return\n";
    co_return i + 23;
}

auto result = syncWait(bar());
```

Making awaiting thread-safe-ish



`Task<T> Promise<T>`

Making awaiting thread-safeish

```
template<typename T>
struct Promise {
    //...
    auto final_suspend() noexcept {
        struct FinalAwaitable { /*...*/ };
        return FinalAwaitable{};
    }
    //...
    enum class State {
        Started,
        AttachedContinuation,
        Finished
    };
    std::atomic<State> state = { State::Started };
};
```

Making awaiting thread-safeish

```
template<typename T>
struct Promise {
    //...
    auto final_suspend() noexcept {
        struct FinalAwaitable { /*...*/ };

```

```
struct FinalAwaitable {
    bool await_ready() const noexcept { return false; }
    void await_suspend(std::coroutine_handle<Promise<T>> thisCoro) {
        auto &promise = thisCoro.promise();
        const auto oldState = promise.state.exchange(State::Finished);
        if (oldState == State::AttachedContinuation)
            promise.continuation();
    }
    void await_resume() const noexcept {}
};
```

Making awaiting thread-safe-ish

```
template<typename T>
struct Promise {
    //...
    bool isReady() const noexcept {
        // return result.index() != 0;
        return state == State::Finished;
    }
    //...
    bool isReady() const noexcept;
    //...
    std::variant<std::monostate, T, std::exception_ptr> result;
    std::coroutine_handle<> continuation;
    enum class State { Started, AttachedContinuation, Finished };
    std::atomic<State> state = { State::Started };
};
```

Making awaiting thread-safeish

```
template<typename T>  
struct [[nodiscard]] Task {  
    //...
```

If state was Started

compare-exchange **succeeds**

returning **true** → coroutine is **suspended**

If state was Finished

compare-exchange **fails**

returning **false** → coroutine is **not suspended**

```
    promise.continuation = continuation;
```

```
    auto expectedState = State::Started;
```

```
    return promise.state
```

```
        .compare_exchange_strong(expectedState,  
                                State::AttachedContinuation);
```

```
    }
```

```
    //...
```

```
};
```

Iteration 2

```
Task<size_t>
std::cout
const auto
std::cout
    << result
co_return
}

int main()
    auto task
std::cout
}
```



```
file async\n";
'main.cpp' };
n (size "
```

```
read file async
; file
; file
g coro
return (size 120)
read: exiting
```

```
result: 120
Promise: dtor
```

Drawbacks of eager tasks

Thread A

```
void qux() {  
    auto task = readFile();  
    throw "oops...";  
    task.~Task();  
}
```



Thread B

```
continues to execute on thread B  
auto work = [this, coro]() {  
    //...  
    → coro();  
    //...  
};
```



State of the art solution so far: lazy tasks

Use cppcoro by Lewis Baker

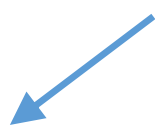
<https://github.com/lewissbaker/cppcoro>

State of the art solution so far: lazy tasks

```
template<typename T>
struct Promise {
    Task<T> get return object() noexcept { return { this }; }
    std::suspend_always initial_suspend() noexcept { return {}; }
    auto final_suspend() noexcept;
    template<typename U>
    void return_value(U &&value)
        noexcept(std::is_nothrow_constructible_v<T, decltype(std::forward<U>(value))>);
    void unhandled_exception()
        noexcept(std::is_nothrow_constructible_v<std::exception_ptr, std::exception_ptr>);
    bool isReady() const noexcept;
    T &&getResult();

    std::variant<std::monostate, T, std::exception_ptr> result;
    std::coroutine_handle<> continuation;
};
```

code from Iteration 1



State of the art solution so far: lazy tasks

```
void qux() {  
    auto task = readFile(); // does not start yet  
    throw "oops..."; // safe to cleanup  
    syncWait(task); // awaiting starts the operation  
}
```

State of the art solution so far: lazy tasks

Use cppcoro by Lewis Baker

<https://github.com/lewissbaker/cppcoro>

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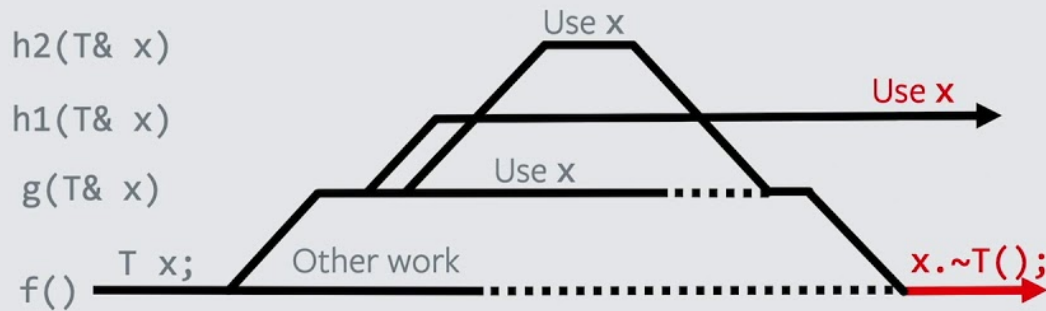
Lewis Baker

Structured Concurrency:
Writing Safer
concurrent code with
coroutines and algorithms

Video Sponsorship Provided By:



Detached Operations



24

<https://youtu.be/1Wy5sq3s2rg>



Thanks for coming!



Understanding C++ coroutines by example


Pavel Novikov

 @cpp_ape

R&D Align Technology

align

Thanks to Lewis Baker for feedback!

I owe you beer 

Slides: <https://git.io/JJvLX>

Bonus slides

getAwaitable()

```
template<typename T>  
auto getAwaitableImpl(T &&a, int) ->  
    decltype(std::forward<T>(a).operator co_await())) {  
    return std::forward<T>(a).operator co_await();  
}
```

```
template<typename T>  
auto getAwaitableImpl(T &&a, long) ->  
    decltype(operator co_await(std::forward<T>(a))) {  
    return operator co_await(std::forward<T>(a));  
}
```

```
template<typename T, typename U>  
T &&getAwaitableImpl(T &&a, U) {  
    return static_cast<T&&>(a);  
}
```

```
template<typename T>  
auto getAwaitable(T &&a) {  
    return getAwaitableImpl(a, 42);  
}
```


ResultOfAwait<T>

```
template<typename T>
using ResultOfAwait =
    std::decay_t<decltype(
        getAwaitable(std::declval<T>()).await_resume()
    )>;
```

tid

```
struct TidMark {  
    friend  
    std::ostream &operator<<(std::ostream &s, TidMark) {  
        s << "(tid=" << std::this_thread::get_id() << ')';  
        return s;  
    }  
} const tid;  
  
std::cout << tid;
```

State machine using coroutines

Events:

```
struct Open {};  
struct Close {};  
struct Knock {};
```

```
enum class State {  
    Closed,  
    Open  
};  
  
struct Door {  
    State state = State::Closed;  
    template<typename E>  
    void onEvent(E);  
};
```

State machine using ~~coroutines~~ switch

```
void onEvent(E) {
    switch (state) {
    case State::Closed:
        if constexpr (isSame<E, Open>) {
            state = State::Open;
        }
        else if constexpr (isSame<E, Knock>) {
            shout("Come in, it's open!"); // no transition
        }
        break;
    case State::Open:
        if constexpr (isSame<E, Close>)
            state = State::Closed;
    }
}
```

State machine using ~~coroutines~~ switch

```
Door door;  
door.onEvent(Open{}); // Closed -> Open  
door.onEvent(Close{}); // Open -> Closed  
door.onEvent(Knock{});  
door.onEvent(Close{}); // Closed -> Closed
```

output:

Come in, it's open!

State machine using coroutines

```
StateMachine getDoor() {  
    for (;;) {  
        //closed  
        auto e = co_await Event<Open, Knock>{};  
        if (std::holds_alternative<Knock>(e)) {  
            shout("Come in, it's open!");  
        }  
        else if (std::holds_alternative<Open>(e)) {  
            // open  
            co_await Event<Close>{};  
        }  
    }  
}
```

State machine using coroutines

```
StateMachine getDoor() {  
  closed:  
    for (;;) {  
      auto e = co_await Event<Open, Knock>{};  
      if (std::holds_alternative<Knock>(e)) {  
        shout("Come in, it's open!");  
      }  
      else if (std::holds_alternative<Open>(e)) {  
        goto open;  
      }  
    }  
  open:  
    co_await Event<Close>{};  
    goto closed;  
}
```

State machine using coroutines

```
template<typename... Events>
struct Event {};

struct StateMachine {
    struct promise_type;

    template<typename E>
    void onEvent(E e);

    ~StateMachine() { coro.destroy(); }
    StateMachine(const StateMachine &) = delete;
    StateMachine &operator=(const StateMachine &) = delete;

private:
    StateMachine(std::coroutine_handle<promise_type> coro) : coro{ coro } {}
    std::coroutine_handle<promise_type> coro;
};
```


State machine using coroutines

```
struct promise_type {
    using CoroHandle = std::coroutine_handle<promise_type>;
    StateMachine get_return_object() noexcept {
        return { CoroHandle::from_promise(*this) };
    }
    std::suspend_never initial_suspend() const noexcept { return {}; }
    std::suspend_always final_suspend() const noexcept { return {}; }
    template<typename... E>
    auto await_transform(Event<E...>) noexcept;
    void return_void() noexcept {}
    void unhandled_exception() noexcept {}

    std::any currentEvent;
    bool (*isWantedEvent)(const std::type_info&) = nullptr;
};
```

StateMachine::promise_type

```
template<typename... E>
auto await_transform(Event<E...>) noexcept {
    isWantedEvent = [](const std::type_info &type)->bool {
        return ((type == typeid(E)) || ...);
    };

    struct Awaitable { /*...*/ };
    return Awaitable{ &currentEvent };
}
```

StateMachine::promise_type

```
struct Awaitable {
    bool await_ready() const noexcept { return false; }
    void await_suspend(CoroHandle) noexcept {}
    std::variant<E...> await_resume() const {
        std::variant<E...> event;
        (void)((
            currentEvent->type() == typeid(E) ?
                (event = std::move(*std::any_cast<E>(currentEvent)), true) :
                false
        ) || ...);
        return event;
    }
    const std::any *currentEvent;
};
```

State machine using coroutines

```
struct StateMachine {  
    //...  
    template<typename E>  
    void onEvent(E &&e) {  
        auto &promise = coro.promise();  
        if (promise.isWantedEvent(typeid(E))) {  
            promise.currentEvent = std::forward<E>(e);  
            coro();  
        }  
    }  
    //...  
};
```

State machine using coroutines

```
auto door = getDoor();  
door.onEvent(Open{}); // Closed -> Open  
door.onEvent(Close{}); // Open -> Closed  
door.onEvent(Knock{});  
door.onEvent(Close{}); // Closed -> Closed
```

output:

Come in, it's open!

State machine using coroutines

```
StateMachine getDoor(std::string answer) {
closed:
    for (;;) {
        auto e = co_await Event<Open, Knock>{};
        if (std::holds_alternative<Knock>(e)) {
            shout(answer);
        }
        else if (std::holds_alternative<Open>(e)) {
            goto open;
        }
    }
open:
    co_await Event<Close>{};
    goto closed;
}
```

State machine using coroutines

```
auto door = getDoor("Occupied!");  
door.onEvent(Open{}); // Closed -> Open  
door.onEvent(Close{}); // Open -> Closed  
door.onEvent(Knock{});  
door.onEvent(Close{}); // Closed -> Closed
```

output:

Occupied!