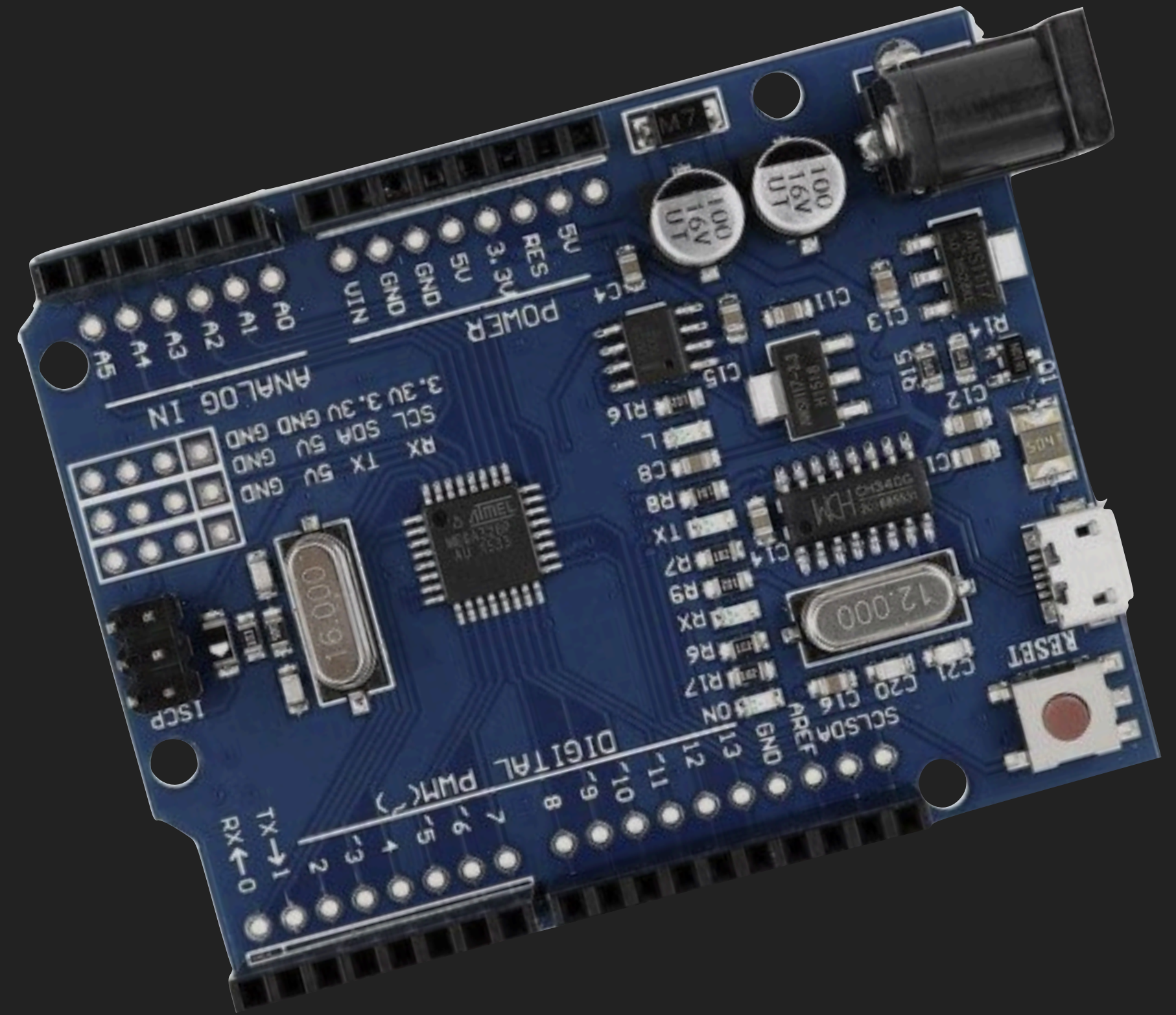


ANTON SYSOEV

DYNAMIC LIBRARIES FOR BARE-METAL





PROBLEM DEFINITION

TARGET SPECIFICATION

- ▶ Installed so far away (Country-wide project)
- ▶ Too difficult to reach installed devices
- ▶ Regular updates of specific parts of firmware
- ▶ Unstable communication channel (wireless)
- ▶ High traffic cost



HARD(TOO HARD)WARE SPECIFIC LIMITATIONS

- ▶ Low flash size
 - ▶ ~64-128K
- ▶ Low RAM size
 - ▶ ~2-4K
- ▶ Poor device connection
 - ▶ GSM Data (9600bps/14400bps theoretically)
 - ▶ GPRS EDGE (Up to 236kbps/s theoretically)
- ▶ MCU Architecture limitations
 - ▶ Harvard architecture (separate instruction and data buses)
 - ▶ Unable to run code from RAM



DYNAMIC CODE IN THE BIG WORLD

COMMON DYNAMIC LIBRARY MECHANISM

- ▶ Library loader
 - ▶ Application loading-time linking
 - ▶ Run-time linking
- ▶ Library export table
- ▶ Toolchain linker

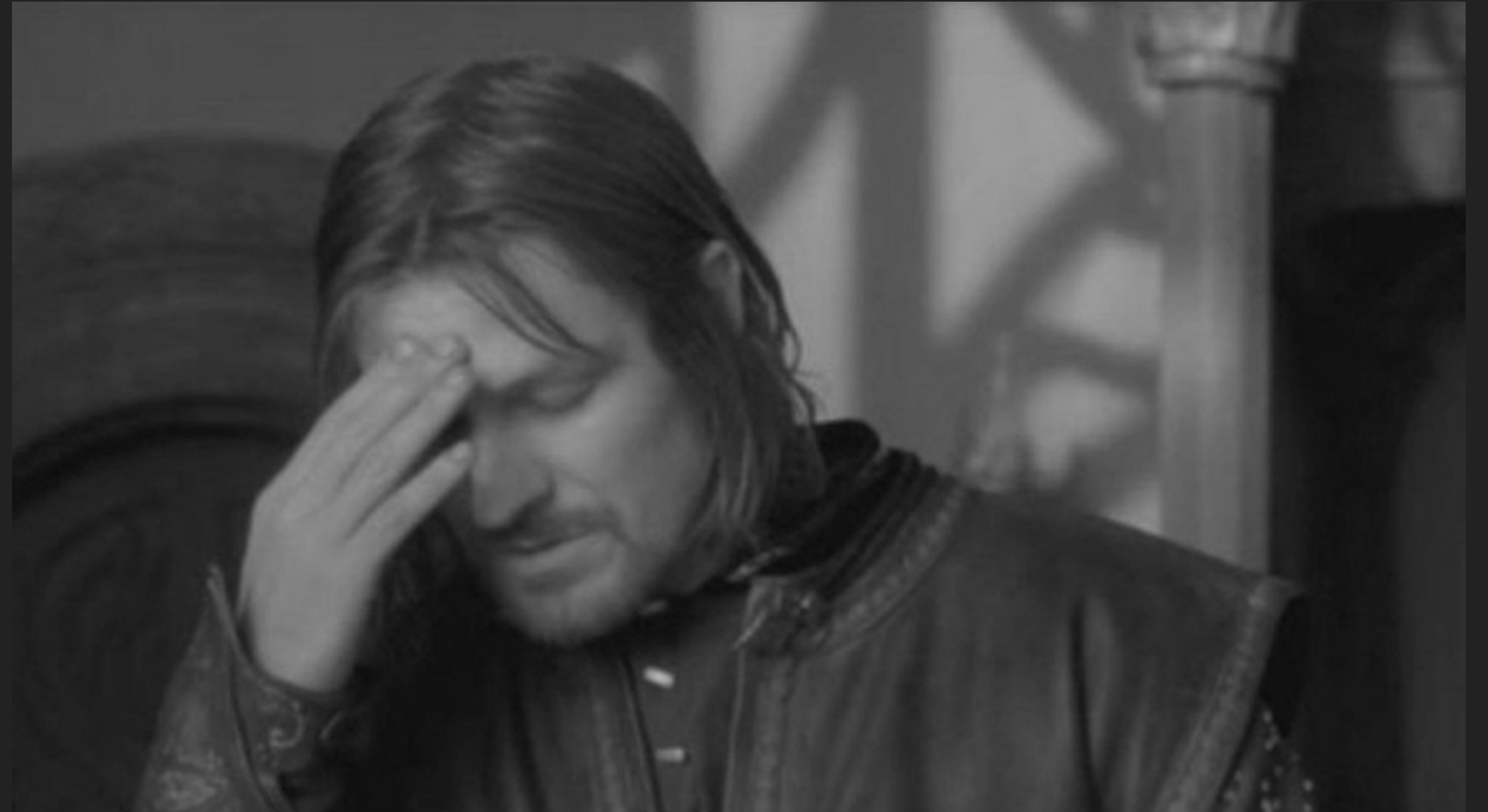
HOW APPLICATION LOADING WORKS

- ▶ Load header
- ▶ Load application sections
- ▶ Load dependent libraries
 - ▶ Library by name
 - ▶ Library by version
- ▶ Link symbols



HOW LIBRARY LOADING WORKS

- ▶ Discover libraries
- ▶ Load header
- ▶ Load sections
- ▶ Set section permissions
- ▶ Load export table
- ▶ Link references



BENEFITS AND DISADVANTAGES

► Benefits

- + Shared code update
- + Memory saving

► Disadvantages

- Runtime overhead
- Maintenance
- Linker/Loader is too complex





SO LET'S DO IT LIKE THEY DO....

WHY CAN'T WE DO THE SAME?

- ▶ No linker
- ▶ No loader
- ▶ No virtual memory
- ▶ No fate





WHAT CAN WE DO?


CUSTOM DYNAMIC FUNCTION ADDRESSING

- ▶ Define “export table”/Library API
- ▶ Inject address relocation
- ▶ Safe update



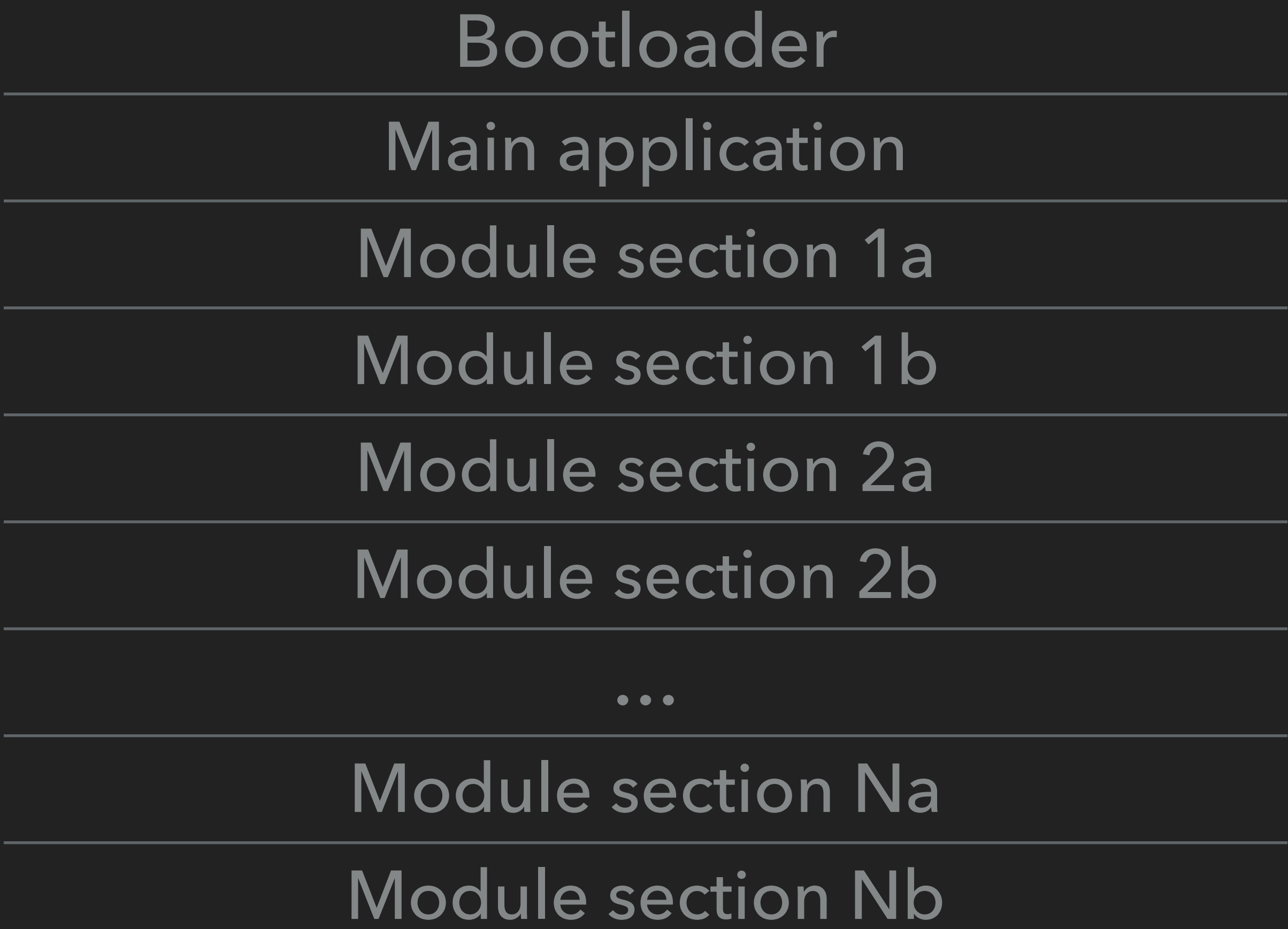
IMPLEMENTATION

PREREQUISITES

- ▶ Slow, small, low resources cheap MCU
 - ▶ Supports Self-Programming Mode
- ▶ (.*)RTOS (?)
- ▶ Hands 
- ▶ Head
- ▶ Patience

DEFINE FIRMWARE ARCHITECTURE

- ▶ Bootloader section
- ▶ Application block
 - ▶ Main application section
 - ▶ Module sections



COMMON MODULE DESIGN

- ▶ Define module API

- ▶ Function prototype should be as flexible as possible

```
int foo(void *arg) // ideal function prototype (Joke!)
```

- ▶ Function set should be evolutionarily stable

- ▶ API Versioning

- ▶ Atomic modules

- ▶ Avoid using of external (even stdlib) functions

JUMP-TABLE

- ▶ Define API table

```
typedef struct _my_api{
    unsigned int active;
    int section;
    int version;
    int (*foo1)(int arg1);
    int (*foo2)(int arg1, int arg2);
    func_ptr reserved[MAX_API_FUNCTIONS-2];
} my_api_t;
```

- ▶ Declare Module section

- ▶ Fill in the API structure

```
my_api_t my_api = {
    UINT_MAX,
    UINT_MAX,
    API_VERSION,
    &foo1,
    &foo2};
```



FLASH MEMORY INTERNALS

COMMON TERMS

- ▶ Limited resources
 - ▶ Can not be programmed an infinite number of times
 - ▶ No error checking out of the box
 - ▶ Write operation may fail
 - ▶ Flash damaging is possible
- ▶ I/O misbalanced
 - ▶ Long time to write
 - ▶ Short time to read

FLASH ORGANIZATION

- ▶ Memory units
 - ▶ Erase sector
 - ▶ Write page

Erase sector 0	Write page 0
	Write page 1
Erase sector 1	Write page 2
	Write page 3
.....	
Erase sector N	Write page M-1
	Write page M

FLASH PROGRAMMING

- ▶ Flash programming sequence:

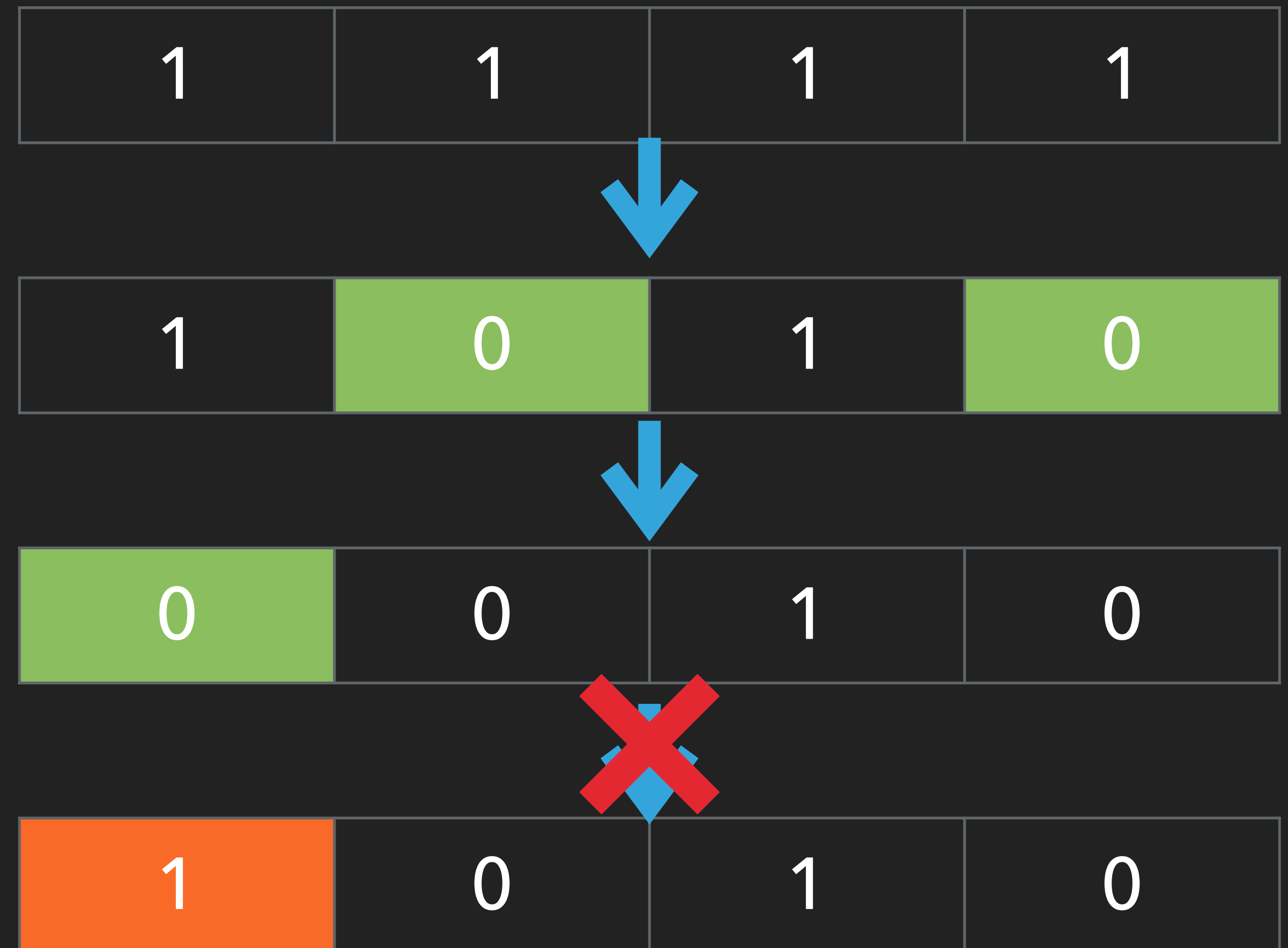
- ▶ Erase page

- ▶ Write page

- ▶ Bit programming rules

- ▶ 1 -> 0 ✓

- ▶ 0 -> 1 ✗

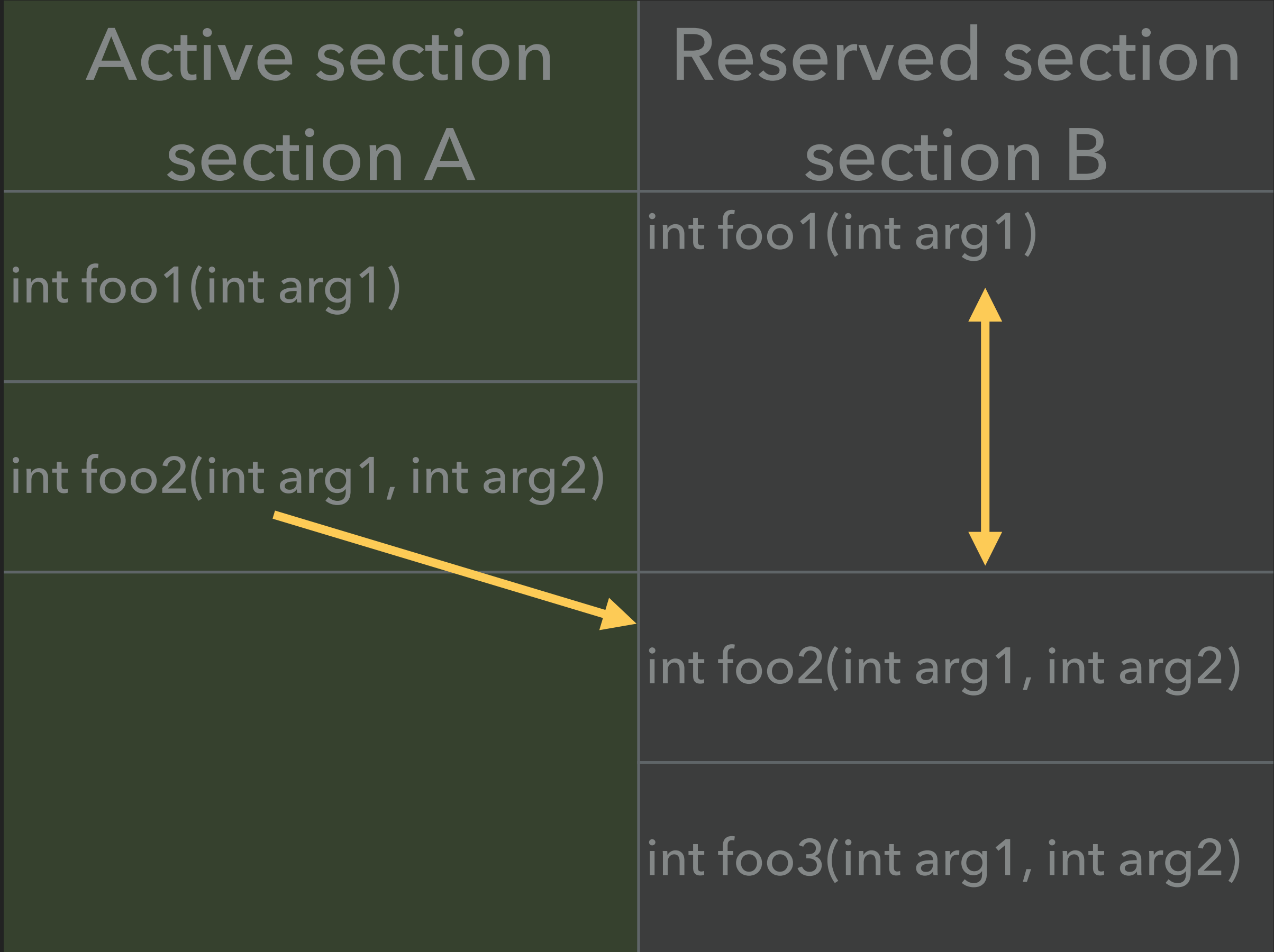




ONE DOES NOT SIMPLY UPDATE

MODULE UPDATE

- ▶ Write data to reserved section
- ▶ Upload new jump-table
- ▶ Update jump-table on target
- ▶ Mark active configuration as inactive
- ▶ Reload jump-table (reboot)



LOAD MODULE

- ▶ Looking for actual jump-table
 - ▶ Verify jump-table structure
 - ▶ Fallback
 - ▶ Use previous version
 - ▶ Mark latest version as damaged
- ▶ Init module API
 - ▶ Initialize API structure in RAM

Jump-table 0

Jump-table 1


...

Jump-table N

JUMP-TABLE JOURNAL

- ▶ Journal-type storage
- ▶ Records markers
 - ▶ Free
 - ▶ Active
 - ▶ Inactive
 - ▶ Damaged

	Free	0xFF	0b11111111
	Active	0xAF	0b10101111
	Inactive	0xAA	0b10101010
	Damaged	0xA0	0b10100000



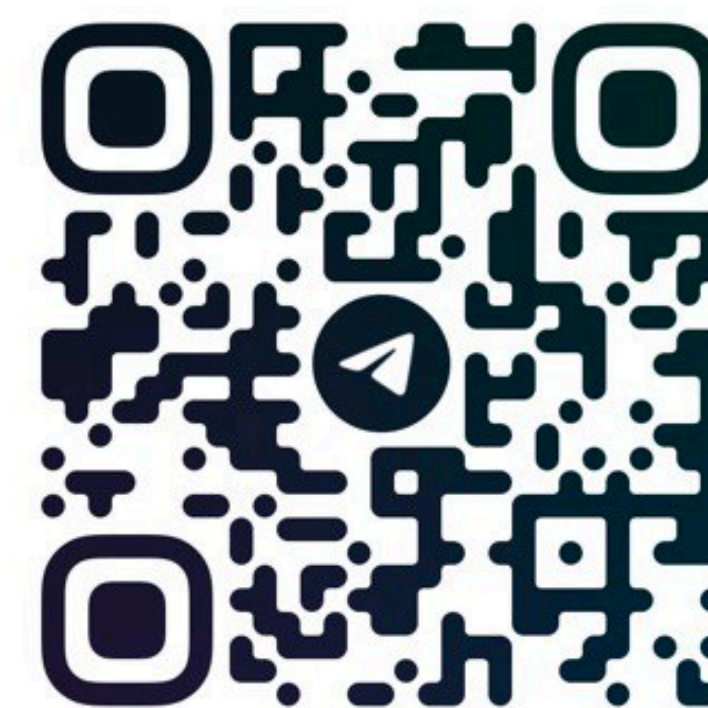
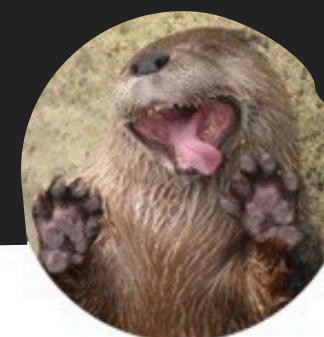
FINAL WORDS



BEHIND THE SCENE

- ▶ Inter-module interaction
 - ▶ Shared module jump-tables
 - ▶ Modules compatibility
- ▶ MCU specific features
 - ▶ on-board/internal EEPROM
 - ▶ on-board FRAM
 - ▶ ARM instruction set mode
- ▶ External code storage

THANK YOU!!!



@BLACK_TONY